



Farnav N30 GNSS USER GUIDE



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Stronger signal, easy to fix

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Preface

Copyright

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Trademarks

All product and brand names mentioned in this publication are trademarks of their respective holders.

Safety Warnings

The Global Navigation Satellite System (GNSS) comprises several distinct satellite constellations, each of which is under the jurisdiction of a specific government entity. These entities bear the sole responsibility for ensuring the accuracy of their respective systems and for maintaining the integrity of their satellite networks.

Do not rely solely on the device for critical navigation decisions. The GNSS signals may be affected by atmospheric conditions, satellite availability, signal blockage, etc.

Be aware of the limitations of GNSS accuracy. It provides positioning information with a certain level of accuracy, but errors (including manual error) and deviations can occur.

Avoid prolonged exposure to strong magnetic fields, as they may interfere with the operation of the device and affect its accuracy.

Do not dismantle or modify the device. Any unauthorized modification may result in malfunction or damage and void the warranty.

Follow all instructions provided in the user manual for proper handling, charging, and maintenance.

FCC Statement

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the

user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation. Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

CE Interference Statement

Declaration of Conformity: Hereby, EFIX Geomatics Co., LTD. declares that this F6 is in compliance with the essential requirements and other relevant provisions of Directive 2014/53/EU. A copy of the Declaration of conformity can be found at EFIX Geomatics Co., LTD.



Brazil

Este equipamento não tem direito à proteção contra interferência prejudicial e não pode causar interferência em sistemas devidamente autorizados. Para maiores informações, consulte o site da ANATEL-www.anatel.gov.br.

Conformity to Japanese regulations

Japanese Radio Law and Japanese Telecommunications Business Law Compliance.

- This device is granted pursuant to the Japanese Radio Law and the Japanese Telecommunications Business Law.
- This device should not be modified (otherwise the granted designation number will become invalid).

1 Introduction

The N30 GNSS receiver removes barriers to portability without sacrificing performance. Featuring full GNSS technology, it offers best-in-class GNSS signal tracking even in a harsh environment, enabling GNSS surveying beyond usual constraints. The N30 GNSS incorporates the latest innovations such as an inertial module (IMU) providing automatic pole-tilt compensation in a very compact design.

1.1 Safety Information

Warnings and Cautions

An absence of specific alerts does not mean that there are no safety risks involved.

A Warning or Caution information is intended to minimize the risk of personal injury and/or damage to the equipment.



WARNING - A Warning alerts you to a potential misused or wrong setting of the equipment.



CAUTION - A Caution alerts you to a possible risk of serious injury to your person and/or damage to the equipment.

1.2 Regulations and Safety

The receivers contain a built-in wireless modem for signal communication through Bluetooth® wireless technology or through external communication datalink. Regulations regarding the use of the wireless modem vary greatly from country to country. In some countries, the unit can be used without obtaining an end-user license. However, in some countries, the administrative permissions are required. For license information, consult your local dealer. Bluetooth® operates in license-free bands.

Before operating a N30 GNSS receiver, determine if authorization or a license to operate the unit is required in your country. It is the responsibility of the end-user to obtain an operator's permit or license for the receiver for the location or country of use.

Use and Care

This receiver is designed to withstand the rough environment that typically occurs in the field. However, the receiver is high-precision electronic equipment and should be treated with reasonable care.



CAUTION - Operating or storing the receiver outside the specified temperature range will cause irreversible damage.

1.3 Technical Support

If you have a problem and cannot find the information you need in this manual or EFIX website (www.Efix-geo.com), contact your local Efix dealer from which you purchased the receiver(s).

If you need to contact Efix technical support, please contact us by email (support@Efix-geo.com).

1.4 Disclaimer

Before using the receiver, please make sure that you have read and understood this User Guide, as well as the safety information. Efix holds no responsibility for the wrong operation by users and for the losses incurred by the wrong understanding about this User Guide. However, Efix reserves the rights to update and optimize the contents in this guide regularly. Please contact your local Efix dealer for new information.

1.5 Your Comments

Your feedback about this user guide will help us to improve it in future revision. Please email your comments to support@Efix-geo.com.

2 Getting Started with N30

2.1 About the Receiver

The FARNAV N30 is a compact, lightweight GNSS receiver designed to deliver top-tier precision and efficiency for professional surveyors. With its 1608-channel GNSS, Full-Star technology, and 4D AUTO-IMU, N30 ensures continuous accuracy in any terrain.

The real-time AR vision stakeout feature simplifies complex staking tasks, boosting efficiency by 50%. its lightweight 450g design, combined with IP68 durability, makes it ideal for fieldwork under extreme conditions. Whether it's for real-time RTK or challenging environments, N30 provides surveyors with the tools to complete projects faster and more accurately than ever before.

The receiver can be used as the part of an RTK GNSS system with landstar software. Moreover, user can download the GNSS data that recorded in the internal memory of receiver to a computer.

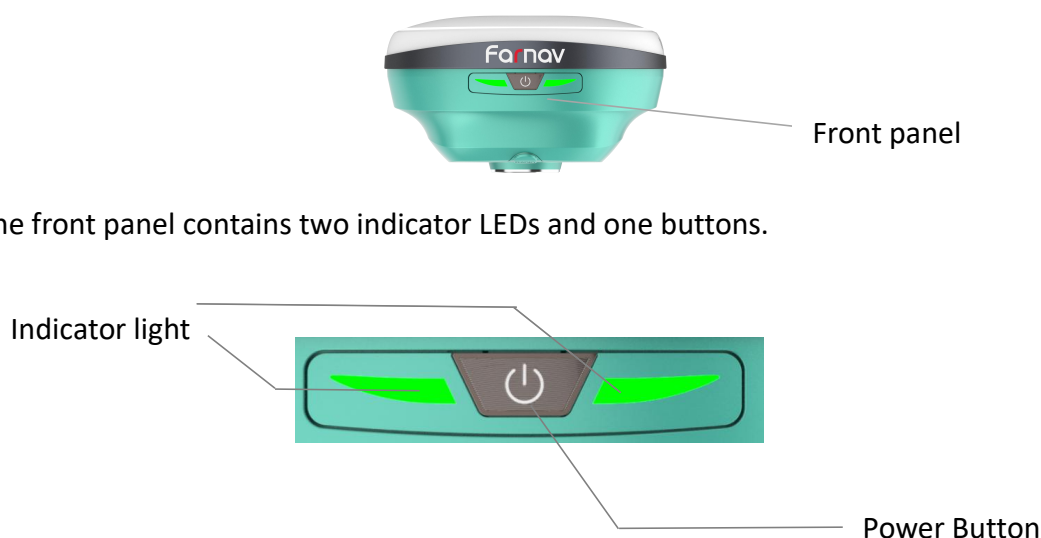
To configure the receiver for performing a wide variety of functions, you can use the web interface by connecting the receiver with PC or smartphone through Wi-Fi.

2.2 Parts of the Receiver

Power Button is located on the front panel. SMA port and USB Type-C port are located on the bottom of the unit.

2.2.1 Front Panel

The following figure shows a front view of the receiver.



Name	Description
Indicator light	✓Indicates whether the receiver is transmitting/receiving differential data. ✓As a Base station: successfully transmitting differential data, flash yellow light. ✓As a Rover station: tracking satellites will flash red light, successfully receiving differential data from Base station will flash yellow light when it is single or float, flash green light when it is fixed. ✓Shows the number of satellites that the receiver has tracked. ✓When the receiver is searching for satellites, the red LED flashes once every 5 seconds. ✓When the receiver tracks N satellites, the red LED blinks N times per second, pauses for 5 seconds, and then blinks N times again. ✓Indicated charging status ✓The power light shows yellow when charging ✓The power light shows green when fully charged

2.2.2 Camera

The following two figures show the bottom view of the receiver:



2.2.3 Receiver Ports

The lower housing contains one SMA port, one USB Type-C communication.



Port	Name	Description
	USB Type-C port	This port is a USB Type-C connector that supports USB communications. Users can use USB Type-C Cable supplied with the system to download the logged data to a computer.
	SMA port	Connect a radio antenna to internal radio of the receiver. And this connector is not used if you are using an external radio.

2.3 Batteries and Power

2.3.1 Built-in batteries

The receiver has an built-in non-removable Lithium-ion battery.

2.3.2 Charging the Battery

The rechargeable Lithium-ion battery is supplied partially charged. Charge the battery completely before using it for the first time. Charge via USB Type-C port.



WARNING – Charge and use the rechargeable Lithium-ion battery only in strict accordance with the instructions. Charging or using the battery in unauthorized equipment can cause an explosion or fire and can result in personal injury and/or equipment damage.

To prevent injury or damage:

- Do not charge or use the battery if it appears to be damaged or leaking.
- Charge the Lithium-ion battery only in a Farnav product that is specified to charge it. Be sure to follow all instructions that are provided with the battery charger.
- Discontinue charging a battery that gives off extreme heat or a burning odor.
- Use the battery only in Farnav equipment that is specified to use it.
- Use the battery only for its intended use and according to the instructions in the product documentation.

2.3.3 Battery Safe



WARNING – Do not damage the rechargeable Lithium-ion battery. A damaged battery can cause an explosion or fire and can result in personal injury and/or property damage.

To prevent injury or damage:

- Do not expose the battery to fire, high temperature, or direct sunlight.
- Do not immerse the battery in water.
- Do not drop or puncture the battery.

2.3.4 External Power Supply

Provide the external power to the receiver by the USB Type-C Cable + Power Adapter.

The Power Adapter is connecting with AC power of 100-240V, the output port of the Power Adapter connects with the USB Type-C Cable.



2.4 Product Basic Supply Accessories

2.4.1 Base Kit Basic Supply

Item	Picture
N30 GNSS Receiver	
SMA Whip Antenna(410-470MHz)	
Power Adapter	
USB Type-C	
H.I. Tape	
Extension pole(30cm)	
Tribrach with optical plummet	
Auxiliary H.I. Tool	
Transport Hard Case	
Tribrach Adaptor	

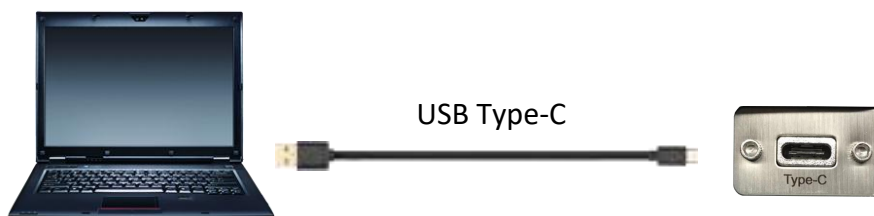
2.4.2 Rover Kit Basic Supply

Item	Picture
N30 GNSS Receiver	
SMA Whip Antenna(410-470MHz)	
Power Adapter	
USB Type-C	
Range Pole (AR)	
Auxiliary H.I. Tool	
Transport Hard Case	

2.5 Connecting to an Office Computer

The receiver can be connected to an office computer via a USB Type-C. Before you connect to the office computer, ensure that the receiver is powered on.

The following figure shows how to connect to the computer for serial data transfer or settings:

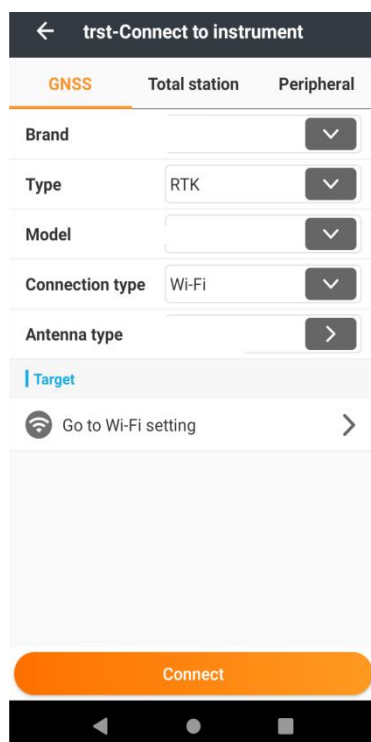


2.6 Connecting to a Controller

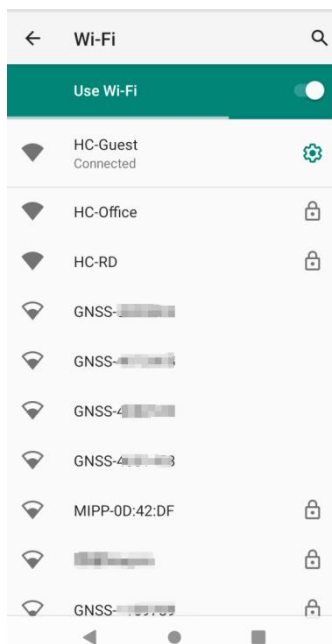
2.6.1 Connecting via Wi-Fi with Landstar Software

Turn on the controller → run Landstar → tap **Connect**.

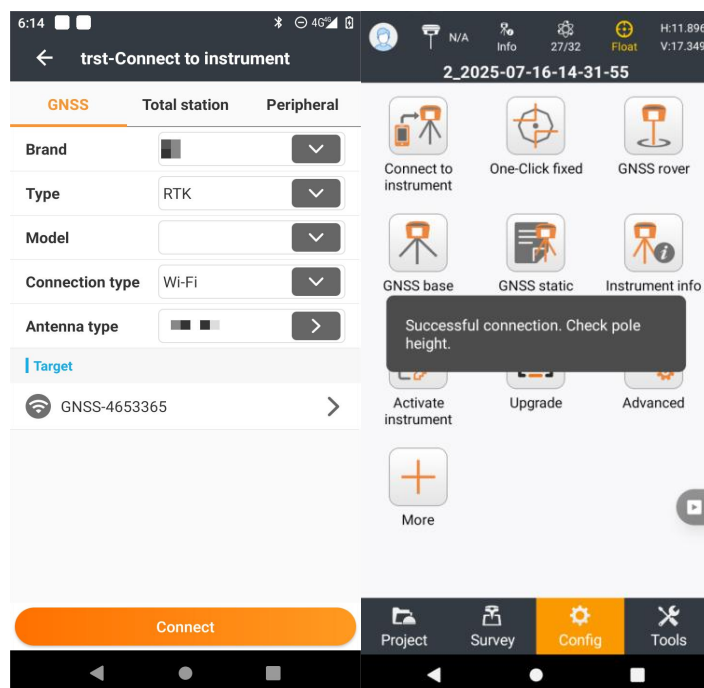
In the Connect screen, select **Farnav** for the Brand field, **N30** for Device Type field, **WIFI** for Connection Type field.



Tap the Click to select WI-Fi to select the hot spot → Switch on the WiFi module by the top switch → select the target device in the WIFI target list



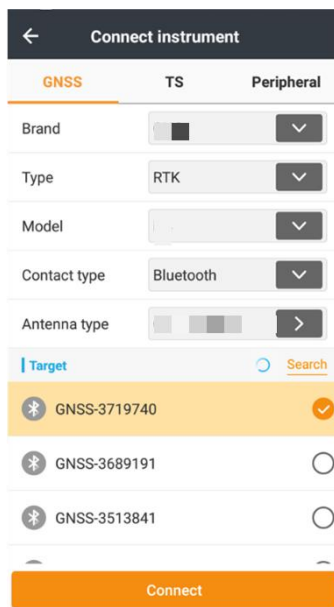
Tap the **Connect** button to build the connection.



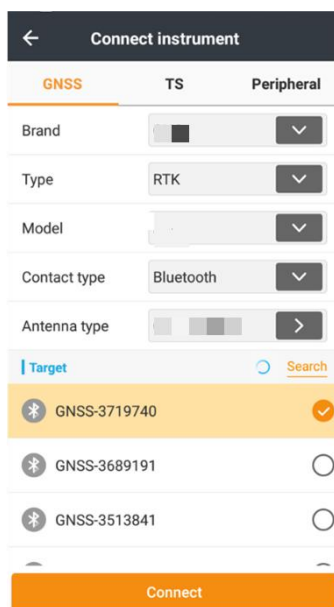
2.6.2 Connecting via Bluetooth with Landstar Software

Turn on the controller → run Landstar → go to **Config** main menu → tap **Connect**.

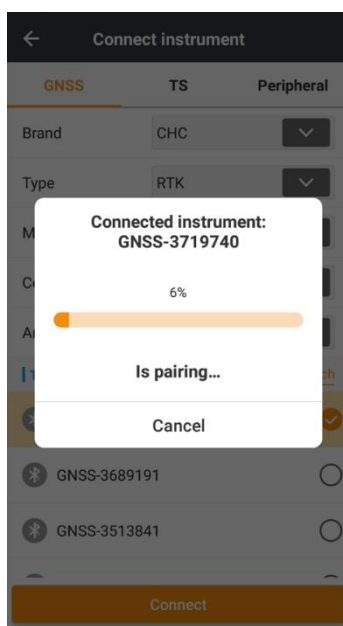
In the *Connect* screen, select Farnav for the **Brand** field, **N30** for *Device Type* field, **Bluetooth** for *Connection Type* field.



Tap the **Search** to search Bluetooth device around → Switch on the Bluetooth module by the top switch → Tap Pair new device → select the target device in the list → Tap back button → select the target device in the Bluetooth target list.



Tap the **Connect** button to build the connection.



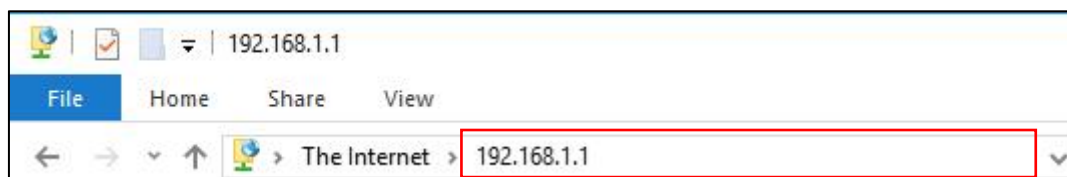
2.7 Downloading Logged Data

Data logging involves the collection of GNSS measurement data over a period at a static point or points, and subsequent post-processing of the information to accurately compute baseline information. Data logging using receivers requires access to suitable GNSS post-processing software such as the eOffice Software.

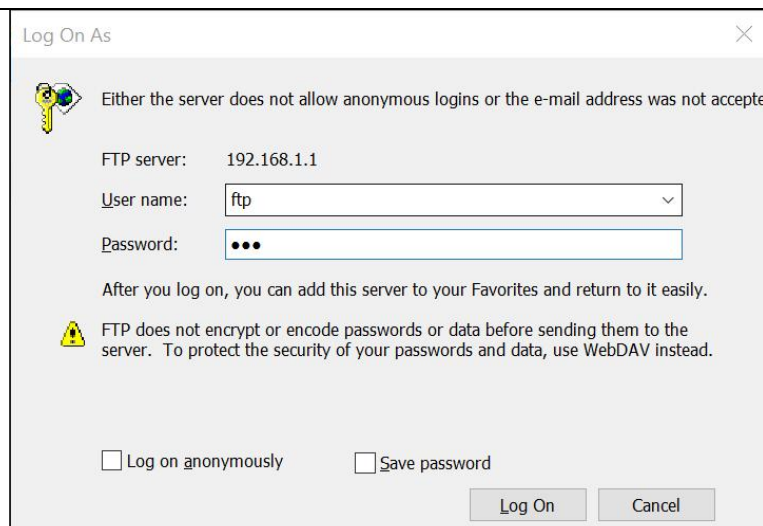
2.7.1 FTP Download

The procedures of downloading logged data through FTP are as follows:

- (1) Switch on the receiver, search its Wi-Fi in the computer and connect.
- (2) After the successful connection, open the file manager in the computer and input "ftp://192.168.1.1" in the address box.



- (3) Input user name and password, the default user name and password are "ftp".



(4) Double click the folder “repo_receiver SN” (take 3225804 as example), you will see 2 folders. The “push_log” folder is used to save the log files, and the "record_1" folders are used for store static data.



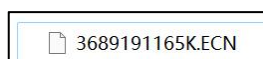
(5) Double click the folder that you have configured to store the static data, you will see the folder(s) created by the N30 system automatically and named by the date which is decide by GPS time when you start to log data.



(6) Select the destination folder and double click it, two folders named as different data format (ECN and rinex) will be displayed.



(7) Select the data format that you configured to save the static data, you will find the static raw data.



Notes: For ecn files, the name of the file is represented as XXXXXXDDDNN, where XXXXXX is the SN of the receiver, DDD is day of year, and NN is the recording session.

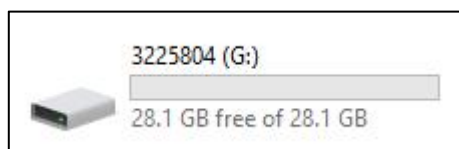


WARNING – The static data will be saved in the first logging session, the “record_1” folder, by default. Old files will be deleted if the storage space is full. If you configure not to auto delete old files when the memory is low, the receiver will stop data logging.

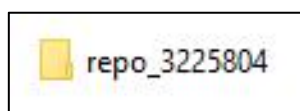
2.7.2 USB Download

The procedures of downloading logged data in the receiver are as follows:

(1) Switch on the receiver and connect it with a computer by Type-C. After the successful connection, a removable disk named as the Serial Number (SN) of the receiver will appear on the computer.

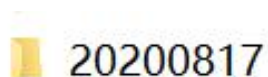


(2) Double click the removable disk and you will see the folder named as “repo”.



(3) Double click the folder “repo_receiver SN”, you will see 2 folders. The “push_log” folder is used to save the log files, and the “record_1” folders are used for store static data.

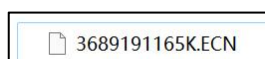
(4) Double click the folder that you have configured to store the static data, you will see the folder(s) created by the N30 system automatically and named by the date which is decide by GPS time when you start to log data.



(5) Select the destination folder and double click it, and then two folders named as different data format (ecn and rinex) will be displayed.



(6) Select the data format that you have configured to save the static data, you will find the static raw data.



Tip – For ECN files, the name of the file is represented as XXXXXXDDDNN, where XXXXXX is the SN of the receiver, DDD is day of year, and NN is the recording session.



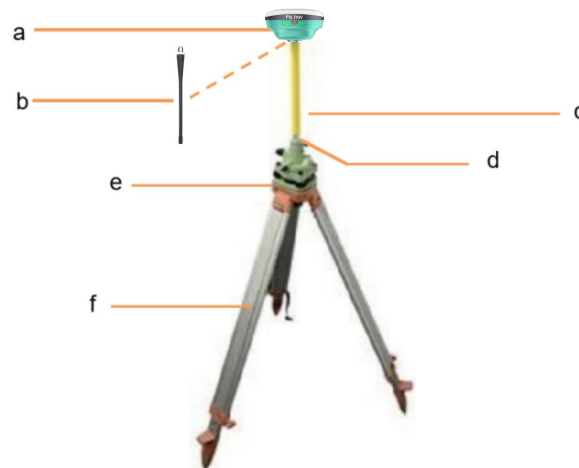
WARNING – The static data will be saved in the first logging session, the “record_1” folder, by default. Old files will be deleted if the storage space is full. If you configure not to auto delete old files when the memory is low, the receiver will stop data logging.

3 Equipment Setup and Operation

3.1 Base Station Setup

For good rover operation, the following base station setup guidelines are recommended:

Components:



No.	Name
a	N30 GNSS receiver
b	SMA Whip Antenna
c	Extension pole (30 cm)
d	Tribrach adaptor
e	Tribrach w/ Opti
f	Aluminum tripod

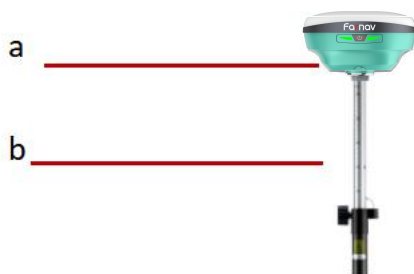
Steps:

- (1) Put tripod in the target position, center and level it roughly.
- (2) Place and lock the tribrach in the tripod.
- If work as a UHF base station**, the SMA Whip Antenna need to be connected to the receiver.
- (3) Connect the receiver to external battery by using external power cable if necessary.
- (4) Connect the receiver to external storage disk by using USB cable if necessary.
- (5) Turn on the receiver by pressing the power button for 3 s.
- (6) Measure the antenna height by using H.I. tape and auxiliary H.I. tool.
- (7) Switch on the data controller and connect it to the receiver.
- (8) Use software to configure the receiver as UHF base mode.

3.2 Rover Station Setup

For good performance, the following rover station setup guidelines are recommended:

Components



No.	Name
a	N30 GNSS receiver
b	2M range pole w/bag

Notice: Keep the receiver fully charged.

If work as a UHF rover station, the SMA Whip Antenna need to be connected to the receiver.

- (1) Turn on the receiver by pressing the power button for 3 s.
- (2) Switch on the data controller and connect it to the receiver.
- (3) Use software to configure the receiver as cellular rover or UHF rover mode.
- (4) Use software to start survey.

3.3 Working with the Tilt Compensation

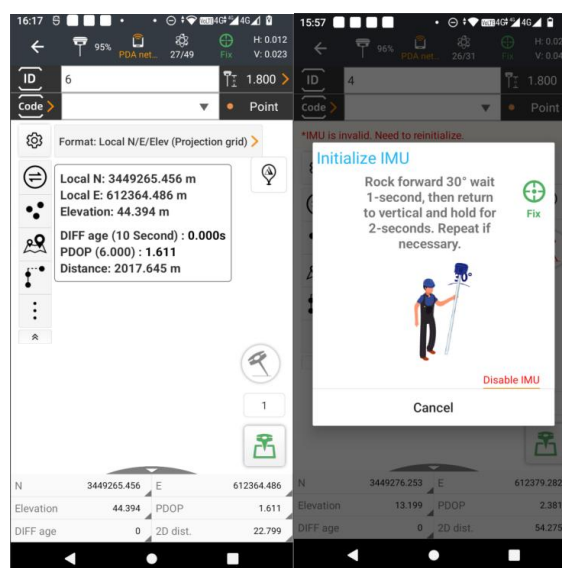
N30 use 200 Hz AUTO-IMU, automatic pole tilt compensation for automatic inertial navigation initialization, and the user do not need to calibrate it manually any more.

After enable the tilt survey, the N30 IMU can be ready after a few steps walk or a bit movement automatically.

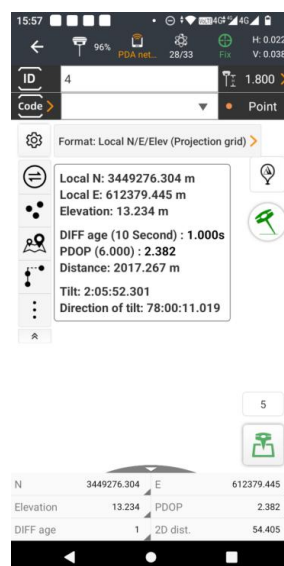
3.3.1 Operation Steps

(1) Open Landstar-> Tap PT Survey-> Tap  to activate tilt measurement.

(2) Shake around according to the procedures in the interface to do initialization.

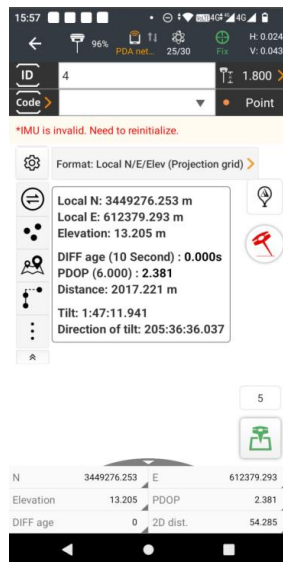


(3) This icon  will appear when the initialization is successful.



(4) Enter the Name and Antenna, then tap  point will be collected and store to Points automatically.

(5) When this icon  appears, the text will show “*IMU is invalid. Need to reinitialize.” at the top of interface.



(6) Tap  to close tilt compensation.

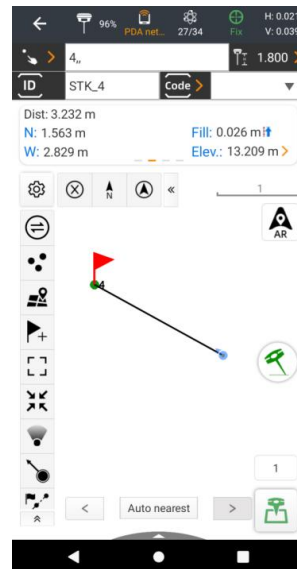
3.3.2 Notes of using tilt measurement

1. At the beginning of initialization, the pole height of the instrument should be the same as that antenna height in the software.
2. In the process of tilt measurement, if the controller shows that “Tilt is not available, please measure in alignment” (red), please shake RTK slightly from left to right or back to front until the reminder disappears.
3. The controller will prompt “Tilt is not available, please measure in alignment” when the receiver is stationary over 30 seconds or the pole hit the ground toughly.
4. The pole cannot be shaken when point is collected.
5. Initialization is required:
 - when the RTK is turned on every time;
 - when IMU module is turned on every time;
 - when receiver drops at working;
 - when the pole is tilted more than 65 degree;
 - when the receiver is stationary more than 10 minutes;
 - when the RTK rotates too fast on the matching pole (2 rounds per second);
 - when the pole hit the ground toughly.

3.4 Stakeout functions

3.4.1 Point stakeout

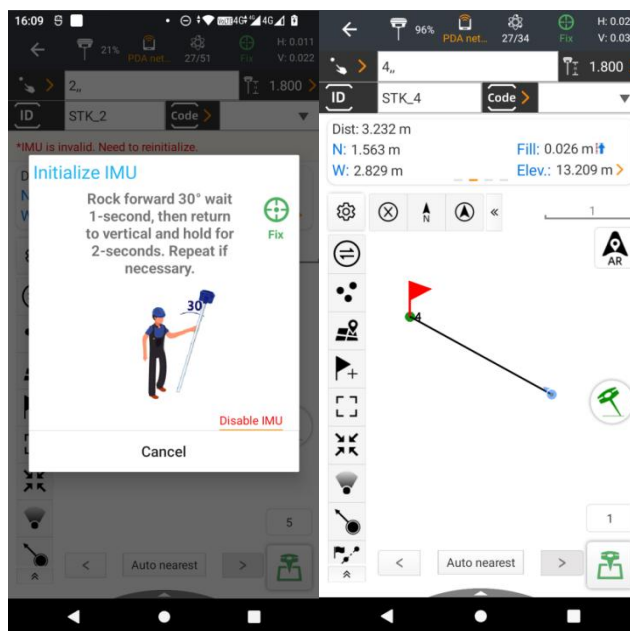
(1) Open the Point Stakeout interface, tap the point-selection icon in the upper-left corner to enter the Point Management screen, choose the point you want to stake out, then tap OK in the lower-right corner. The selected point will appear in the stakeout interface; simply follow the displayed direction and distance to perform the stakeout.



3.4.2 AR stakeout

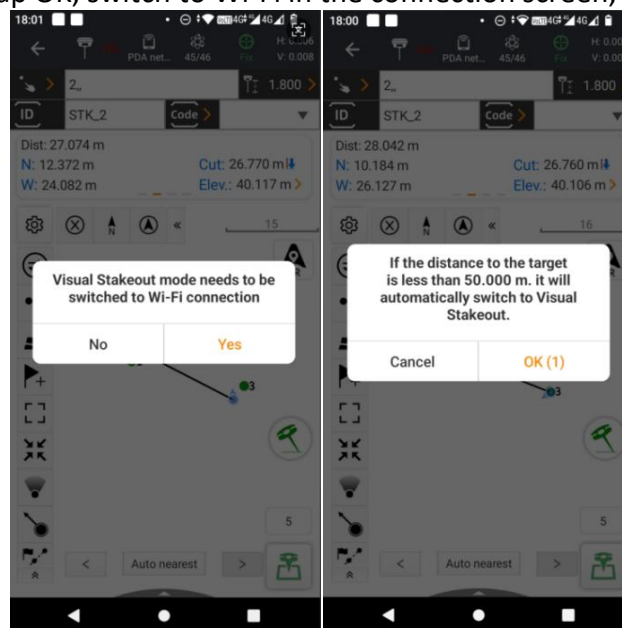
For point stakeout, ensure IMU is initialized. Select the point, tap the “AR” icon on the right, then follow the on-screen direction and distance

(1) Open Point Stakeout, enter the pole height, and tap the Tilt icon to enable tilt compensation. Follow the on-screen prompts to initialize; when successful, the icon turns green .



(2) Tap the AR icon to start AR stakeout.

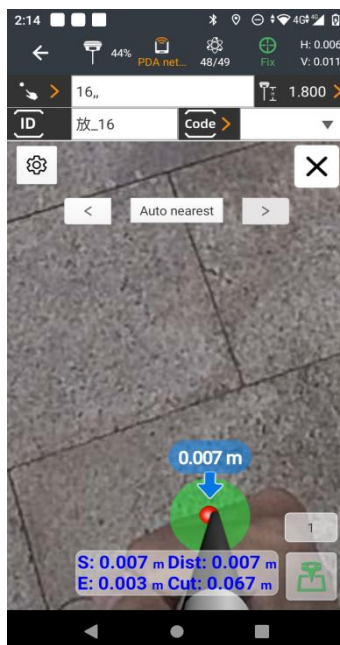
If the controller is connected via Bluetooth, a prompt will appear: “Vision mode requires Wi-Fi.” Tap OK, switch to Wi-Fi in the connection screen, and reconnect.



(3) In Vision Settings, we can adjust the switch distance: the front camera is used from 50 m to 3 m, and the bottom camera takes over within 3 m.



(4) In the video, the target stakeout point appears as a red dot. When the virtual pole tip touches the dot, you've reached the point. Tap the stakeout icon and the point is automatically saved.



Note:

When the stakeout target point has a height, it is necessary to input the height of the target point as 0 or the actual height.

PDA and receiver camera should face the same direction.

3.4.3 Notes of using Vision Camera

1. At the beginning of initialization, the pole height of the instrument should be the same as that antenna height in the software.
2. In the process of tilt measurement, if the controller shows that “Tilt is not available, please measure in alignment” (red), please shake RTK slightly from left to right or back to front until the reminder disappears.
3. The controller will prompt “Tilt is not available, please measure in alignment” when the receiver is stationary over 30 seconds or the pole hit the ground toughly.
4. The pole cannot be shaken when point is collected.
5. Initialization is required:
 - when the RTK is turned on every time;
 - when IMU module is turned on every time;
 - when receiver drops at working;
 - when the pole is tilted more than 65 degree;
 - when the receiver is stationary more than 10 minutes;
 - when the RTK rotates too fast on the matching pole (2 rounds per second);
 - when the pole hit the ground toughly.

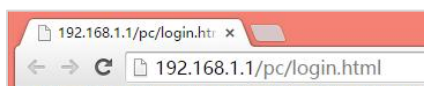
4 Configuring Through a Web Browser

Supported browsers:

- Google Chrome
- Microsoft Internet Explorer version 10, or higher

To connect to the receiver through a web browser:

1. Turn on the Wi-Fi of the receiver.
2. Search the wireless network named as GNSS-XXXXXXX (the SN of your receiver) on your computer, and then establish the connection.
3. After the successful connection between your computer and the receiver, enter the IP address (192.168.1.1) of the receiver into the address bar of the web browser on your computer:



4. The web browser prompts you to enter a login account and password:

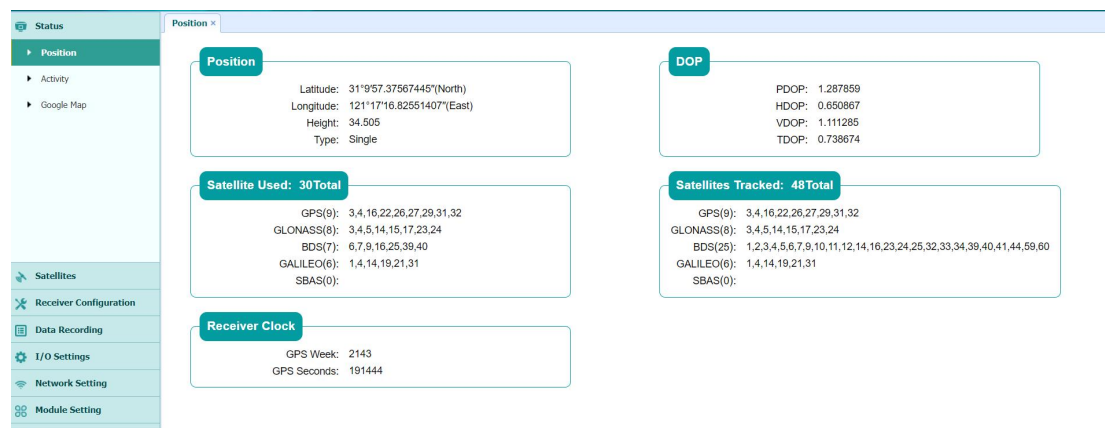


The default login account for the receiver is:

- Login Account: admin
- Password: password

Note – Tick remember me option, and then the browser will remember the Login Account and Password you entered.

5. Once you log in, the web page appears as follows:



This web page shows the configuration menus on the left of the browser window, and the setting on the right. Each configuration menu contains the related Submenus to configure the receiver and monitor receiver performance.

This chapter describes each configuration menu.

To view the web page in another language, select the corresponding language name from the dropdown list on the upper right corner of the web page.

Currently, these languages are available:



4.1 Status Menu

This menu provides a quick link to review the receiver's position information, satellites tracked, runtime, current data log status, current outputs, available memory, and more.

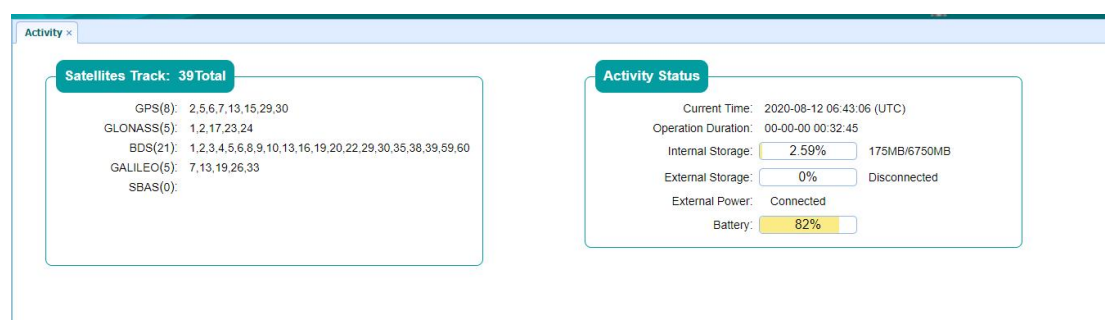
4.1.1 Position Submenu

This page shows the relevant position information about the receiver's position solution which including the position, DOP values, satellites used and tracked, and the receiver clock information.



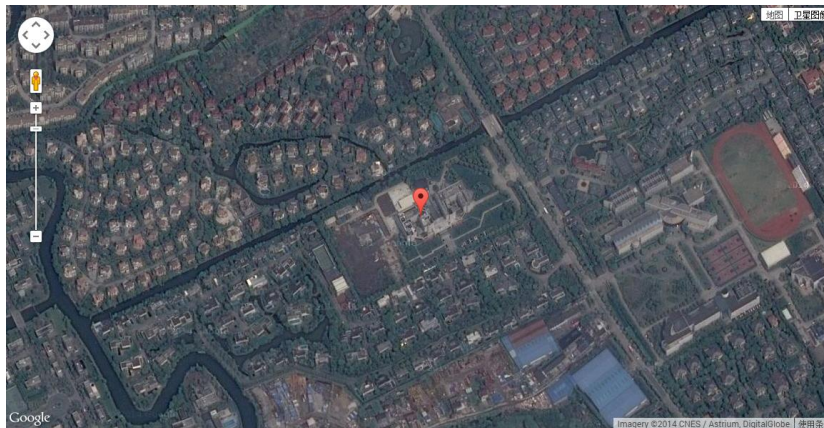
4.1.2 Activity Submenu

Lists several important items to help you understand how the receiver is being used and its current operating condition. Items include the identities of currently tracked satellites, internal and external storage usage rate, how long the receiver has been operational, state of the internal battery, power source state. With this information, it is easy to tell exactly what functions the receiver is performing:



4.1.3 Google Map Submenu

Tap this submenu to show the location of the receiver on Google map.



4.2 Satellites Menu

Use the Satellites menu to view satellite tracking details and enable/disable GPS, GLONASS, BDS and Galileo constellations. These menus include tabular and graphical displays to provide all required information on satellite tracking status.



4.2.1 Tracking Table Submenu

Provides the status of satellites tracked in general, such as the satellite ID, satellite type, attitude angle, azimuth angle, L1 SNR, L2 SNR, L5 SNR and enable/disable status of each one.

Tracking Table							
All GPS GLONASS BDS GALILEO SBAS							
SV	Type	Elevation Angle	Azimuth Angle	L1 SNR	L2 SNR	L5 SNR	Enabled
2	GPS	53	332	45.660	36.420	0.000	Yes
5	GPS	47	258	40.200	34.340	0.000	Yes
6	GPS	51	59	46.460	39.220	47.300	Yes
9	GPS	32	55	42.130	33.920	44.300	Yes
12	GPS	25	265	44.080	34.830	0.000	Yes
17	GPS	30	148	44.390	33.470	0.000	Yes
19	GPS	45	147	44.230	34.510	0.000	Yes
25	GPS	10	303	37.660	31.190	39.240	Yes
4	GLONASS	42	28	46.520	47.890	0.000	Yes
5	GLONASS	81	230	47.930	51.230	0.000	Yes
19	GLONASS	51	99	35.050	46.220	0.000	Yes
20	GLONASS	50	349	40.390	50.220	0.000	Yes
1	BDS	48	146	42.080	42.740	43.530	Yes
2	BDS	36	236	37.350	40.800	40.080	No
3	BDS	52	200	43.130	42.120	44.200	Yes
4	BDS	35	122	37.550	38.470	40.850	Yes
5	BDS	15	256	33.570	35.130	34.650	No
6	BDS	40	179	38.970	38.900	41.820	Yes
7	BDS	11	195	31.840	31.010	35.650	No
8	BDS	61	15	44.190	44.860	46.650	Yes
9	BDS	20	191	36.140	35.200	36.780	Yes
10	BDS	17	217	33.330	34.840	35.540	No
13	BDS	52	331	44.300	42.940	45.260	Yes
4	GALILEO	26	203	37.790	40.350	34.420	Yes
12	GALILEO	54	335	41.650	43.420	39.640	No
19	GALILEO	73	132	39.940	42.290	39.230	Yes
26	GALILEO	10	113	33.220	33.960	31.130	No

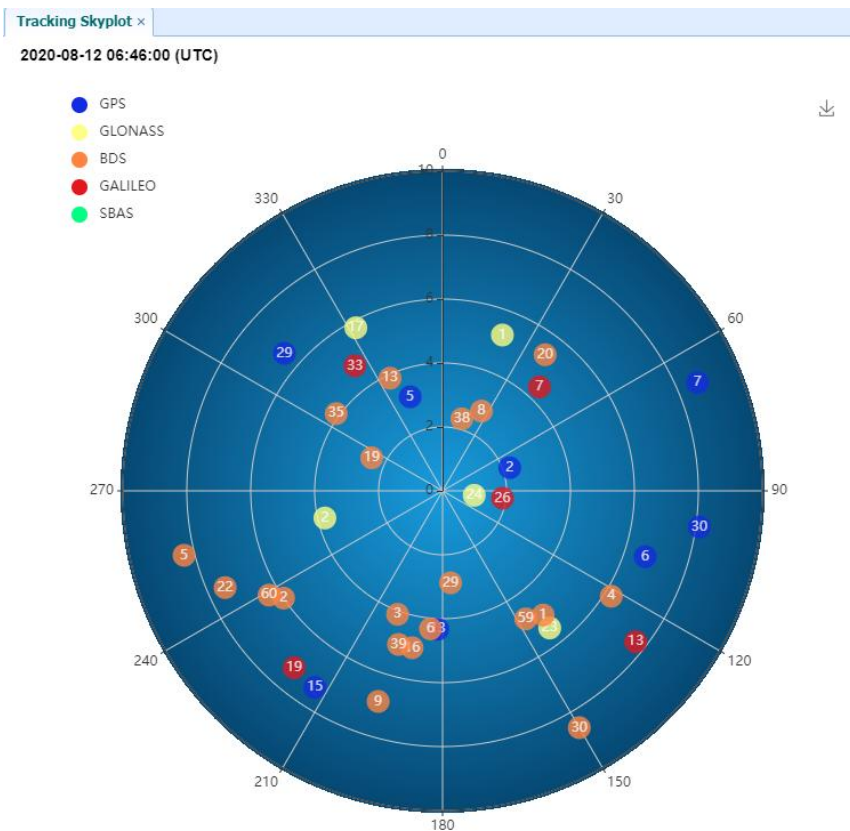
4.2.2 Tracking Info. Table Submenu

The following figure is an example of satellite track diagram page. Users can determine the satellite types and the corresponding SNR of L-band carriers to be displayed in any combination.



4.2.3 Tracking Skyplot Submenu

The following figure is an example of Skyplot page.



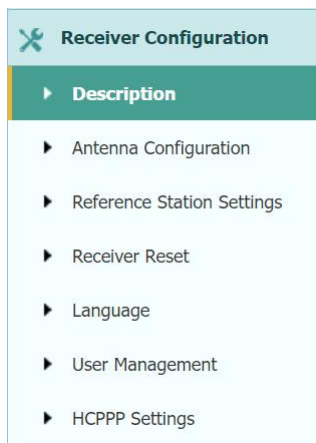
4.2.4 Satellite Activation Submenu

Use this menu to enable or disable satellites.

Satellite Activation			
GPS GLONASS BDS GALILEO SBAS			
Select All Unselect All Confirm Enable All Disable All			
Satellite Id	Enable	Satellite Id	Enable
1	☒	2	☒
3	☒	4	☒
5	☒	6	☒
7	☒	8	☒
9	☒	10	☒
11	☒	12	☒
13	☒	14	☒
15	☒	16	☒
17	☒	18	☒
19	☒	20	☒
21	☒	22	☒
23	☒	24	☒
25	☒	26	☒
27	☒	28	☒
29	☒	30	☒
31	☒	32	☒

4.3 Receiver Configuration Menu

Use this menu to configure settings such as the antenna type and height, elevation mask and PDOP setting, the reference station coordinates, receiver resetting and web interface language:



4.3.1 Description

This submenu shows the receiver information and reference station information, including antenna related information, elevation mask angle, reference station work mode and position, etc.



4.3.2 Antenna Configuration Submenu

Use this screen to configure all the items related to the GNSS antenna. You must enter the correct values for all antenna-related fields, because the choices you make affect the accuracy for logged data and broadcast correction data significantly:

The screenshot shows the 'Antenna Configuration' submenu. It contains the following fields and values:

- Measure Way: Antenna Phase Center (dropdown)
- Antenna manufacturer: EFIX (dropdown)
- Antenna Type: EFIX (dropdown)
- Antenna SN: 9999645 (text input)
- Antenna Height: 2.0000 (text input) (Meter)
- Elevation Mask: 10 (text input)
- PDOP Mask: 6 (text input)

A green 'Save' button is located at the bottom right of the configuration area.

4.3.3 Reference Station Settings Submenu

Use this screen to configure settings such as the station coordinates and the broadcast station identifiers. You must enter accurate information in these fields, as this data affects the accuracy of logged data files and broadcast correction data significantly:

For **Reference Station Mode**:

There are three modes available:

1.Auto Rover: The receiver will serve as a rover after this mode is enabled, and then receive correction data through the working mode set last time.

The screenshot shows the 'Reference Station Settings' submenu. It contains the following fields and values:

- Reference Station Mode: Auto Rover (dropdown)
- Sample for Average:
 - Positioning Constraint: ☒ Single Solution Coordinates ☐ Fixed Solution Coordinates
 - Sampling Amount: 300 (text input) 0% (text input)

Buttons include a green 'Save' button, a green 'Start' button, and a red 'Stop' button.

2.Auto Base: The receiver will serve as a base after this mode is enabled, and then broadcast correction data based on coordinate inputted by user or obtained through autonomous positioning automatically.

Reference Station Settings

Reference Station Mode: Auto Base

Base Station Name: 9999690

Base Station ID: 9999690

Reference Latitude: 31 9 34.56636444 N S

Reference Longitude: 121 10 42.49352449 E W

Reference Height: 50.4336

Save

Sample for Average

Positioning Constraint: ☒ Single Solution Coordinates ☐ Fixed Solution Coordinates

Sampling Amount: 300 0%

Start Stop

Coordinates transfer threshold value(Meter): 0

Save

Base list

ID	Height	Latitude	Longitude
1	15.8100	31 9 58.23544000 N S	121 17 15.28542028 E W

3.Manual Base: The receiver will serve neither as a base nor a rover after this mode is enabled. Users need to configure the receiver manually.

For Reference Latitude and Reference Longitude:

Reference Station Mode: Manual Base

Base Station Name: 9999690

Base Station ID: 9999690

Reference Latitude: 31 9 34.56636444 N S

Reference Longitude: 121 10 42.49352449 E W

Reference Height: 50.4336

Use Current Position Save

Sample for Average

Positioning Constraint: ☒ Single Solution Coordinates ☐ Fixed Solution Coordinates

Sampling Amount: 300 0%

Start Stop

There are mainly three methods to enter the reference coordinates and shown as follows:

4.Acquire Current Position: Click this button to acquire current position obtained through autonomous positioning automatically.

5.Manual Input: Manually input the coordinate of a control point.

6.From CORS: After the receiver logging in CORS, the software can record the coordinate of current position based on fix solution.

For Sample for Average:

Users can determine the positioning limit and sampling amount. The positioning limit falls into two types:

1.Single Solution Coordinates: Collect the coordinates of receiver obtained through

autonomous positioning.

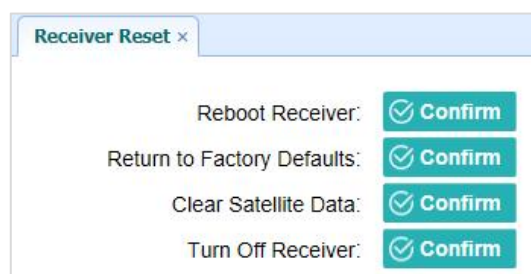
2.Fixed Solution Coordinates: Only collect coordinates of receiver with a fixed solution.

After the configuration of positioning limit and sampling amount, click  to carry out sampling and averaging → the progress bar will show the progress → the result will be served as the coordinate of current position.

If users need to save the changes, please tap  button.

4.3.4 Receiver Reset Submenu

Use this screen to completely or partially reset the receiver:



4.3.5 Languages Submenu

Use this screen to select the web interface language:



4.3.6 User Management Submenu

User Management x

User Management

Add

Save

Delete

Modify Anti-theft password

ID	User Name	Password
1	admin	*****
2	admin1	*****
3	admin2	*****

4.4 Data Recording Menu

Use the Data Logging menu to set up the receiver to log static GNSS data and to view the logging settings. You can configure settings such as observable rate, recording rate, continuous logging limit, and whether to auto delete old files when memory is low. This menu also provides the controls for the FTP push feature:

Data Recording

Log Settings

FTP Push Settings

FTP Push Log

4.4.1 Log Settings Submenu

Here shows the data logging status, including internal and external storage usage and data logging status of each session. Also, users can configure the data logging settings for each session, including recording name, store location, storage limit, store formats, start time, etc.

Log Settings x

Store Info

	Position	Total Storage	Storage Available
1	Internal Storage	6750MB	6576MB
2	External Storage	0MB	0MB

Attention: Total assigned storage size should be less than 6GB. It will stop recording when the storage is full.

Record Info

Clear All

Recording Number	File Name	Activated	Log Status	Setting Parameter	Switch	Clear Data
1	record1	Yes	Recording	Modify Detail	ON OFF	Clear

To edit the settings of each session, click the **Modify** button to the right of the required session, and then the Recording Edit screen appears:

Recording Edit

Auto Record: ☐ Yes ☒ No

Sample Interval: 1Hz

Elevation Mask: 15 (°)

Duration Time: 60 (Minute)

Site Name: 3689191base

Antenna Height: 0.0000

Measure Way: Vertical Height

Storage Format: ECN

RINEX Version: 3.0x

Compress Rinex Data: ☐ Yes ☒ No

Advanced

Save Back

Click advanced to see more settings.

Start Date: ☐ Yes ☒ No

Apply Time: ☐ Yes ☒ No

Integral Point Store: ☐ Yes ☒ No

Circulating Memory: ☒ Yes ☐ No

the data overwritten first file after storage space is full

Repeat Observations: ☒ Yes ☐ No

Turn on to record a single observation. Turn off to record repeated observations.

Store Location: Internal Storage

Assigned Storage: 6000 (MB)

Observer: EFIX

Observe Agency: EFIX

FTP Push:

- ☒ Close
- ☐ 1:ftp server 1
- ☐ 2:ftp server 2
- ☐ 3:ftp server 3

Save Back

In this screen, you can configure all the data logging parameters, and determine whether the recording files will be affected by the FTP Push. The parameters are mainly as follows:

- **Auto Record:** on or off.
- **Sample Interval:** Select the observable rate from the dropdown list.
- **Elevation Mask:** Enter the elevation mask.
- **Duration Time:** Set the duration of data logging.
- **Site Name:** Enter the name of the site.
- **Antenna Height:** the measured height value.
- **Measure way:** Antenna Phase Center, Vertical Height, Slant Height
- **Storage Format:** Select the format of the data store.
- **RINEX Version:** OFF, 3.02, 2.11
- **Start Date:** Select Yes or No option to determine whether to auto record start date.

➤ **Apply Time:** Select Yes or No option to determine whether to auto record apply time.

➤ **Integral Point Store:** Select Yes or No option to determine whether to allow receiver to save data every hour.

➤ **Circulating Memory:** Select Yes or No option to determine whether to auto delete old files if the storage space is full.

➤ **Repeat Observations:** Select Yes or No option to determine whether to turn on to record a single observation.

➤ **Store Location:** Internal Storage, External Storage.

➤ **Assigned Storage:** The assigned memory size of current thread(for example, Record 1) is 10000MB

➤ **Observer:** Enter the name of observer.

➤ **Observer Agency:** Enter the name of observer agency.

➤ **FTP Push:** Decide whether to push the stored files to the FTP server of your choice.

Tap  **Save** button to save the settings and back to the Log Settings screen. Also, users can click  **Back** to abandon the changed settings and back to Log Settings screen.

Note – To modify data logging parameters, make sure the data logging session is switched off.

To switch on or off **ANY** data logging session, tap the **ON** or **OFF** button on the right of the required session.

To delete the recorded files of **ANY** data logging session, tap the **Clear** button on the right of the required session.

To delete the recorded files of **ALL** data logging sessions, tap the **Clear ALL Accounts** button.

4.4.2 FTP Push Settings Submenu

Use this screen to configure the receiver to push stored files to the FTP server of your choice. Only files that are configured to use FTP push are transmitted.

Record Info				
Server ID	Server IP	Remote Directory	Server Description	Modify
1	192.168.3.72	/repo/first	ftp server 1	
2	192.168.3.72	/repo/second	ftp server 2	
3	192.168.3.72	/repo/third	ftp server 3	

Tap **Modify** button on the right of the required FTP server and the FTP Push Settings screen appears:

FTP Push Settings

Server IP: 192.168.3.72

Port: 21

Remote Directory: /repo/first

Local directory: /mnt/repo_3225804

Server Description: ftp server 1

User Name: ftpuser1

Password:

Save

Back

4.4.3 FTP Push Log Submenu

Shows the related information about the recorded files that be pushed. And users can tap **Clear Ftp Send Log** button in the upper right corner to clear the log of FTP Push operations.

FTP Push Log x

Record Info

Clear FTP Push Log

Server ID	Push File	File Size	Push Time	Push Successful Or Not
20				

Page 1 of 1

Displaying 0 to 0 of 0 items

4.5 IO Settings Menu



Use the IO Settings menu to set up all receiver outputs and inputs. The receiver can output CMR, RTCM, Raw data, Ephemeris data, GPGLGA, GPGLSV, on TCP/IP, UDP, serial port, or Bluetooth ports.

The following figure shows an example of the screen that appears when you select this submenu. (serial port setting is reserved menu)

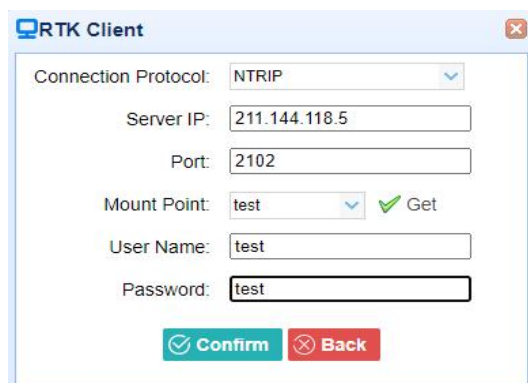
I/O Settings ×					
	Type	Description	Output	Connection Status	Modify
1	RTK Client	211.144.118.5:2102	---	Unconnected	Connect Disconnecting Detail
2	TCP/UDP_Client1/NTRIP Server1	192.168.3.18:9900	---	Unconnected	Connect Disconnecting Detail
3	TCP/UDP_Client2/NTRIP Server2	192.168.3.18:9901	---	Unconnected	Connect Disconnecting Detail
4	TCP/UDP_Client3/NTRIP Server3	192.168.3.18:9902	---	Unconnected	Connect Disconnecting Detail
5	TCP/UDP_Client4/NTRIP Server4	192.168.3.18:9903	---	Unconnected	Connect Disconnecting Detail
6	TCP/UDP_Client5/NTRIP Server5	192.168.3.18:9904	---	Unconnected	Connect Disconnecting Detail
7	TCP/UDP_Client6/NTRIP Server6	192.168.3.18:9905	---	Unconnected	Connect Disconnecting Detail
8	TCP Server/NTRIP Caster1	9901	---	Closed	Connect Disconnecting Detail
9	TCP Server/NTRIP Caster2	9902	---	Closed	Connect Disconnecting Detail
10	TCP Server/NTRIP Caster3	9903	---	Closed	Connect Disconnecting Detail
11	TCP Server/NTRIP Caster4	9904	---	Closed	Connect Disconnecting Detail
12	Serial Port	115200	---	---	Settings
13	Bluetooth	GNSS-3225804	GPGLGA:5s	---	Settings
14	Radio	456.0500MHz	---	---	Settings

In this submenu, users can configure 6 types of input and output settings.

1. RTK Client

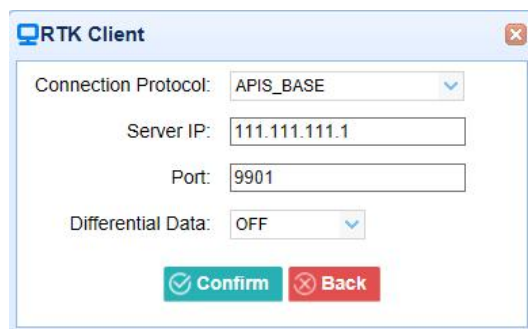
After configuring the settings of RTK client, users can log on CORS or APIS. Tap the **Connect** button to the right → the *IO Settings* screen will appear → choose one of the connection protocols among the NTRIP, APIS_BASE, APIS_ROVER and TCP → configure the related parameters → click **Confirm** to log on CORS or APIS.

➤ Connection Protocol: NTRIP



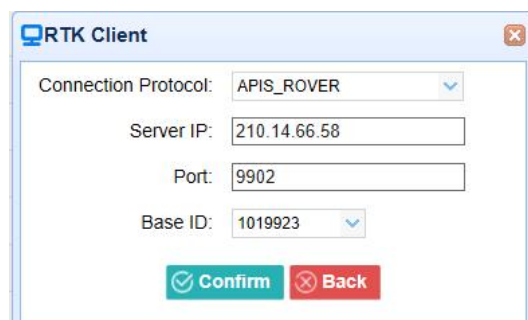
The screenshot shows the 'RTK Client' window with the 'Connection Protocol' set to 'NTRIP'. The fields are filled with the following values: Server IP: 211.144.118.5, Port: 2102, Mount Point: test (with a green checkmark and 'Get' text next to it), User Name: test, and Password: test. At the bottom, there are 'Confirm' and 'Back' buttons.

➤ Connection Protocol: APIS_BASE



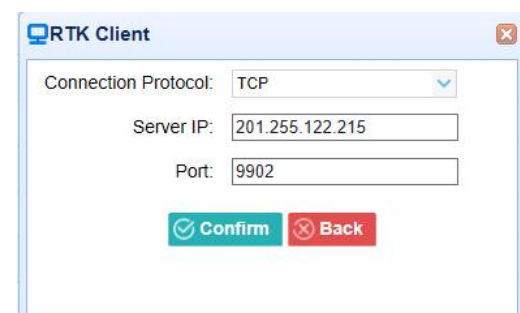
The screenshot shows the 'RTK Client' window with the 'Connection Protocol' set to 'APIS_BASE'. The fields are filled with the following values: Server IP: 111.111.111.1, Port: 9901, and Differential Data: OFF. At the bottom, there are 'Confirm' and 'Back' buttons.

➤ Connection Protocol: APIS_ROVER



The screenshot shows the 'RTK Client' window with the 'Connection Protocol' set to 'APIS_ROVER'. The fields are filled with the following values: Server IP: 210.14.66.58, Port: 9902, and Base ID: 1019923. At the bottom, there are 'Confirm' and 'Back' buttons.

➤ Connection Protocol: TCP

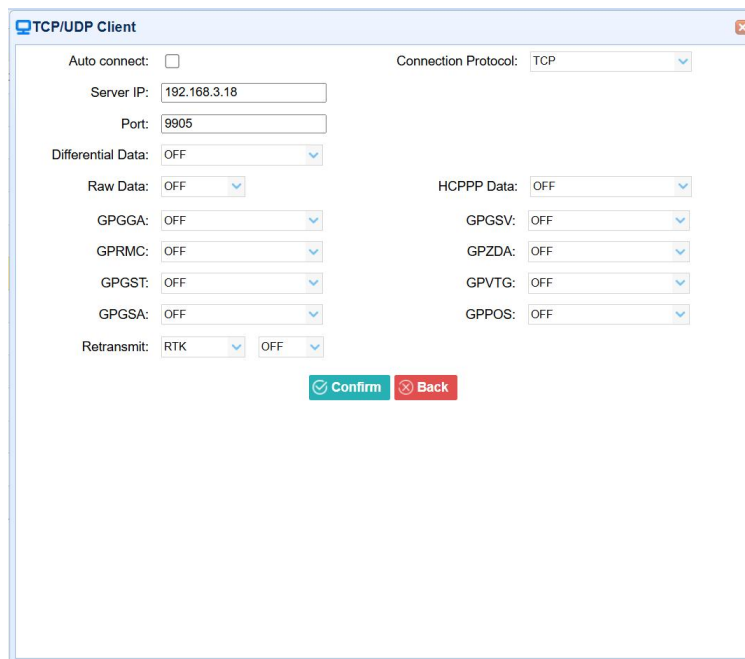


The screenshot shows the 'RTK Client' window with the 'Connection Protocol' set to 'TCP'. The fields are filled with the following values: Server IP: 201.255.122.215, Port: 9902. At the bottom, there are 'Confirm' and 'Back' buttons.

2. TCP/UDP_Client/NTRIP Server

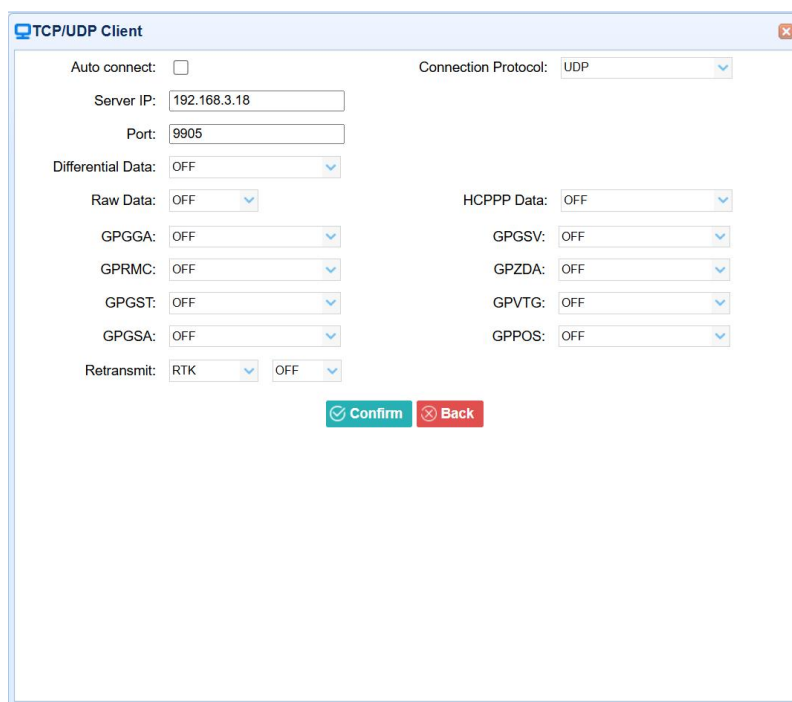
Tap the **Connect** button on the right of required TCP/UDP Client → the *IO Settings* screen will appear → select the connection protocol from TCP, UDP, NTRIP1.0 and NTRIP2.0 → enter the IP and Port of the target server → configure messages that you want to output to the target server → click **Confirm** to save and complete the connection.

➤ Connection Protocol: TCP



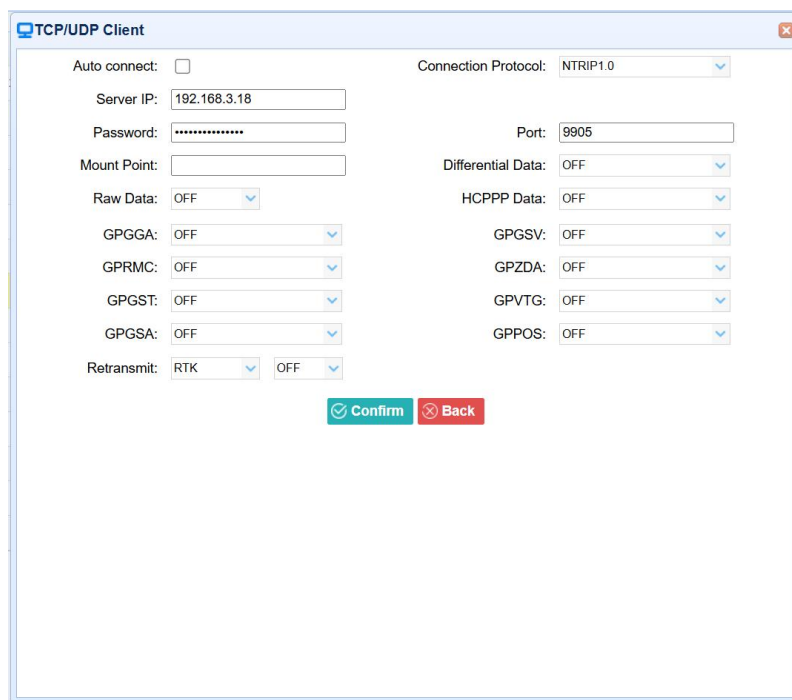
The screenshot shows the 'TCP/UDP Client' configuration window. The 'Connection Protocol' is set to 'TCP'. The 'Auto connect' checkbox is unchecked. The 'Server IP' is '192.168.3.18' and the 'Port' is '9905'. The 'Differential Data' is set to 'OFF'. The 'Raw Data' is set to 'OFF'. The 'HCPPP Data' is set to 'OFF'. The 'GPGGA' is set to 'OFF'. The 'GPRMC' is set to 'OFF'. The 'GPGST' is set to 'OFF'. The 'GPGSA' is set to 'OFF'. The 'Retransmit' is set to 'RTK'. The 'GPGSV' is set to 'OFF'. The 'GPZDA' is set to 'OFF'. The 'GPVTG' is set to 'OFF'. The 'GPPOS' is set to 'OFF'. At the bottom, there are 'Confirm' and 'Back' buttons.

➤ Connection Protocol: UDP



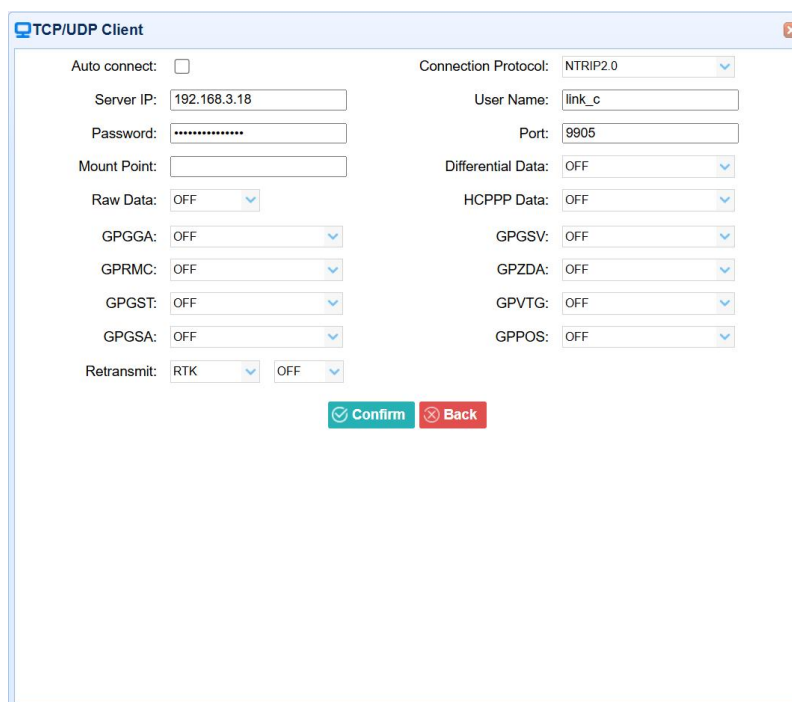
The screenshot shows the 'TCP/UDP Client' configuration window. The 'Connection Protocol' is set to 'UDP'. The 'Auto connect' checkbox is unchecked. The 'Server IP' is '192.168.3.18' and the 'Port' is '9905'. The 'Differential Data' is set to 'OFF'. The 'Raw Data' is set to 'OFF'. The 'HCPPP Data' is set to 'OFF'. The 'GPGGA' is set to 'OFF'. The 'GPRMC' is set to 'OFF'. The 'GPGST' is set to 'OFF'. The 'GPGSA' is set to 'OFF'. The 'Retransmit' is set to 'RTK'. The 'GPGSV' is set to 'OFF'. The 'GPZDA' is set to 'OFF'. The 'GPVTG' is set to 'OFF'. The 'GPPOS' is set to 'OFF'. At the bottom, there are 'Confirm' and 'Back' buttons.

➤ Connection Protocol: NTRIP1.0



The screenshot shows the 'TCP/UDP Client' configuration window. The 'Connection Protocol' is set to 'NTRIP1.0'. The 'Auto connect' checkbox is unchecked. The 'Server IP' is '192.168.3.18', 'Password' is masked with dots, and 'Mount Point' is empty. The 'Port' is '9905'. On the left, 'Raw Data' is OFF, and 'GPGGA', 'GPRMC', 'GPGST', 'GPGSA', and 'Retransmit' (set to RTK) are all OFF. On the right, 'Differential Data', 'HCPPP Data', 'GPGSV', 'GPZDA', 'GPVTG', and 'GPPOS' are all OFF. 'Confirm' and 'Back' buttons are at the bottom.

➤ Connection Protocol: NTRIP2.0



The screenshot shows the 'TCP/UDP Client' configuration window for NTRIP2.0. The 'Connection Protocol' is set to 'NTRIP2.0'. The 'Auto connect' checkbox is unchecked. The 'Server IP' is '192.168.3.18', 'Password' is masked with dots, and 'Mount Point' is empty. The 'Port' is '9905'. On the left, 'Raw Data' is OFF, and 'GPGGA', 'GPRMC', 'GPGST', 'GPGSA', and 'Retransmit' (set to RTK) are all OFF. On the right, 'Differential Data', 'HCPPP Data', 'GPGSV', 'GPZDA', 'GPVTG', and 'GPPOS' are all OFF. A 'User Name' field with 'link_c' is present. 'Confirm' and 'Back' buttons are at the bottom.

3. TCP Server/NTRIP Caster

Tap the **Connect** button to the right of required TCP Server/NTRIP Caster → the **IO Settings** screen will appear → select one of the connection protocols between NTRIP and TCP → configure the other related parameters → click **Confirm** to save the settings and open the server.

➤ Connection Protocol: TCP

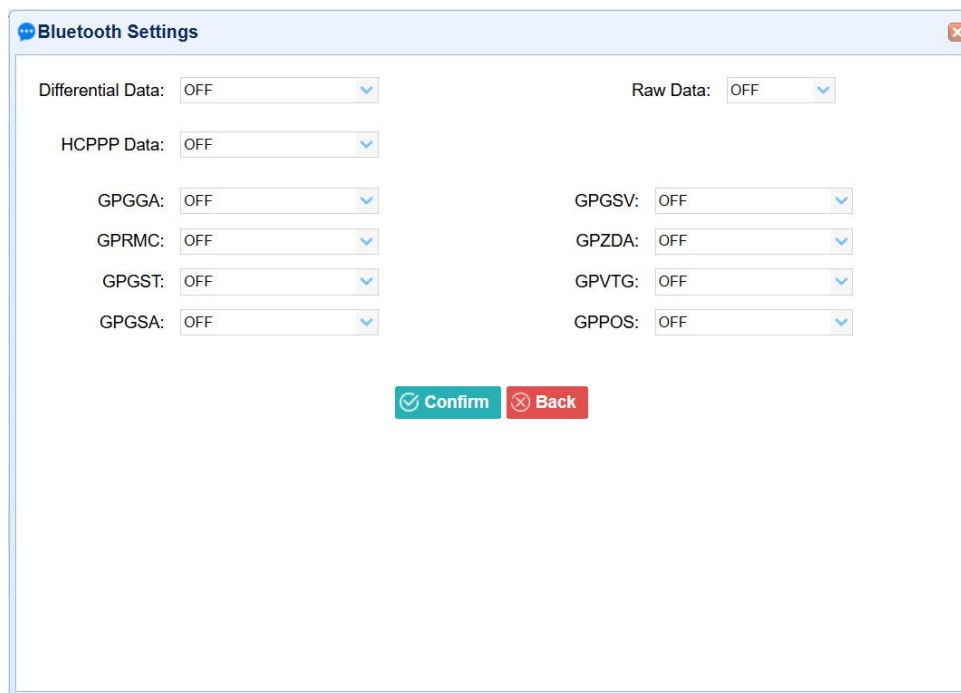
The screenshot shows the 'TCP Server/NTRIP Caster' settings window. The 'Connection Protocol' is set to 'TCP'. The 'Auto connect' checkbox is unchecked. The 'Port' is set to '9901'. The 'Differential Data' is set to 'OFF'. The 'HCPPP Data' is set to 'OFF'. The 'GPGGA' is set to 'OFF'. The 'GPRMC' is set to 'OFF'. The 'GPGST' is set to 'OFF'. The 'GPGSA' is set to 'OFF'. The 'Retransmit' is set to 'RTK'. The 'Raw Data' is set to 'OFF'. The 'GPGSV' is set to 'OFF'. The 'GPZDA' is set to 'OFF'. The 'GPVTG' is set to 'OFF'. The 'GPPOS' is set to 'OFF'. There are 'Confirm' and 'Back' buttons at the bottom.

➤ Connection Protocol: NTRIP

The screenshot shows the 'TCP Server/NTRIP Caster' settings window. The 'Connection Protocol' is set to 'NTRIP'. The 'Auto connect' checkbox is unchecked. The 'User Name' field is empty. The 'Password' field is empty. The 'Port' is set to '9901'. The 'Mount Point' field is empty. The 'Differential Data' is set to 'OFF'. The 'HCPPP Data' is set to 'OFF'. The 'GPGGA' is set to 'OFF'. The 'GPRMC' is set to 'OFF'. The 'GPGST' is set to 'OFF'. The 'GPGSA' is set to 'OFF'. The 'Retransmit' is set to 'RTK'. The 'Raw Data' is set to 'OFF'. The 'GPGSV' is set to 'OFF'. The 'GPZDA' is set to 'OFF'. The 'GPVTG' is set to 'OFF'. The 'GPPOS' is set to 'OFF'. There are 'Confirm' and 'Back' buttons at the bottom.

4. Bluetooth

Tap the **Settings** button to the right of Bluetooth → the *Bluetooth Set* screen will appear → configure the messages that you want to transmit through Bluetooth → click **Confirm** to save the settings and start to transmit.



Bluetooth Settings

Differential Data: OFF

Raw Data: OFF

HCPPP Data: OFF

GPBGA: OFF

GPRMC: OFF

GPGST: OFF

GPGSA: OFF

GPBGSV: OFF

GPZDA: OFF

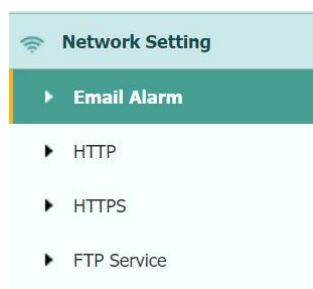
GPVTG: OFF

GPPOS: OFF

Confirm **Back**

4.6 Network Setting Menu

Use this menu to set email alert for specific situation, configure HTTP or HTTPS port, and the username and password of internal FTP site:



Network Setting

▶ **Email Alarm**

▶ HTTP

▶ HTTPS

▶ FTP Service

4.6.1 Email Alarm Submenu

Use this submenu to choose which situation of receiver will be alerted and input the email address.

The screenshot shows the 'Email Alarm' submenu with three sections: 'TO', 'From', and 'Email Alert'. The 'TO' section contains three input fields for email addresses, all pre-filled with 'test@EFIX.com', and a 'Save' button. The 'From' section contains three input fields for 'Account', 'Password', and 'Server Address', with a 'Save' button. The 'Email Alert' section contains four checkboxes for alerting conditions: 'Receiver is powered on', 'External power is off', 'Battery level is low', and 'Ftp push is failed'. A fifth checkbox, 'Receiver(license) will be expired in 7 days', is also present. A 'Save' button is at the bottom of this section.

4.6.2 HTTP Submenu

Use this submenu to configure HTTP port.

The screenshot shows the 'HTTP' submenu with a single input field for 'HTTP Port' set to '80' and a 'Save' button.

4.6.3 HTTPS Submenu

Use this submenu to configure HTTPS port.

The screenshot shows the 'HTTPS' submenu. It features a section titled 'HTTPS' containing an 'Enable HTTPS' toggle with 'Yes' selected and 'No' unselected. Below this is an input field for 'HTTPS Port' set to '443'. A 'Save' button is located at the bottom of the section.

4.6.4 FTP Service Submenu

Use this submenu to configure the user name and password of internal FTP site.

The screenshot shows the 'FTP Service' configuration window. It has a title bar 'FTP Service x'. Inside, there's a teal 'FTP Service' button. Below it, the 'User Name' field contains 'ftp' and the 'Password' field contains three dots. A teal 'Save' button is at the bottom right.

4.7 Module Setting Menu

Use this menu to check module information, configure WiFi, bluetooth, radio related settings.

The screenshot shows the 'Module Setting' menu. It has a header 'Module Setting' with a menu icon. Below it, there's a list of options: 'Description', 'WiFi', 'Bluetooth Settings', and 'Radio Settings'. The 'Description' option is highlighted with a teal bar.

4.7.1 Description Submenu

Use this submenu to check the information of WiFi module, bluetooth module and radio module.

The screenshot shows the 'Description' submenu. It has a title bar 'Description x'. Inside, there are two sections: 'Wi-Fi Information' and 'Radio Information'.
Wi-Fi Information:
 Power Status: ON
 Wifi Mode: Access Point
 MAC: b4:bc:7c:2e:89:46
 Access Point Details
 SSID: GNSS-3269707
Radio Information:
 Radio Type: Integ
 Radio Power: 1W
 OTA Baud Rate: 9600
 Radio Frequency: 463.8125MHz
 Radio Protocol: Transparent
 Radio Frequency Channel: Full Range
 Frequency Range: 410MHz---470MHz

4.7.2 WiFi Submenu

Use this submenu to turn on/off WiFi function and modify password.

WiFi x

WiFi

Power Status: ON OFF

Auto Start: ☒ Yes ☐ No

Internet: ☒ Yes ☐ No

Wifi Mode: Access Point ▼

SSID: GNSS-3225804

Encryption Type: WAP ▼

Password:

Start

4.7.3 Bluetooth Settings Submenu

Use this submenu to turn on/off bluetooth function and modify PIN number.

Bluetooth Settings x

Bluetooth Settings

Local Name: GNSS-3225804

MAC Address: 50:72:24:60:C7:6F

PIN: 1234

Save

4.7.4 Radio Settings Submenu

Use this submenu to turn on/off radio function and configure radio parameters.

Radio Settings ×

Radio Settings

Radio Status: ON ON OFF

Auto Start: ☒ Yes ☐ No

Radio Protocol: Transparent

Channel Bandwidth : 12.5 (kHz)

OTA Baud Rate: 4800

Radio Power: 1W

Radio Frequency: 1 456.050000 (410MHz---470MHz)

FEC: ☐

Save

4.8 Firmware Menu

Use this menu to check the current firmware information, download the system log, update the receiver firmware, download or update the configuration file and register the receiver, and more:

Firmware

▶ **Firmware Info.**

- ▶ Hardware Version
- ▶ Config File
- ▶ System Log
- ▶ User Log
- ▶ Firmware Update
- ▶ GNSS Board Upgrade
- ▶ GNSS Registration

4.8.1 Firmware Info Submenu

Use this submenu to check the current firmware information. The following figure shows an example of the firmware information.

Firmware Version: 2.1.2
Firmware Release Time: 20201127_15084_5439

4.8.2 Hardware Version Submenu

Use this submenu to check the hardware information, including main board version and core board version:

Hardware Version ×

Main Board: 1.1
Core Board: 1.1
PN: A10654430005050004
Board Firmware Version: R3.00Build20868
Number:

4.8.3 Config File Submenu

Use this submenu to update Configuration File.

Config File ×

Download Configuration File : [Download](#)

Update Configuration File: [Browse](#)

[Confirm](#)

4.8.4 System Log Download Submenu

Use this submenu to download the system log of the receiver.

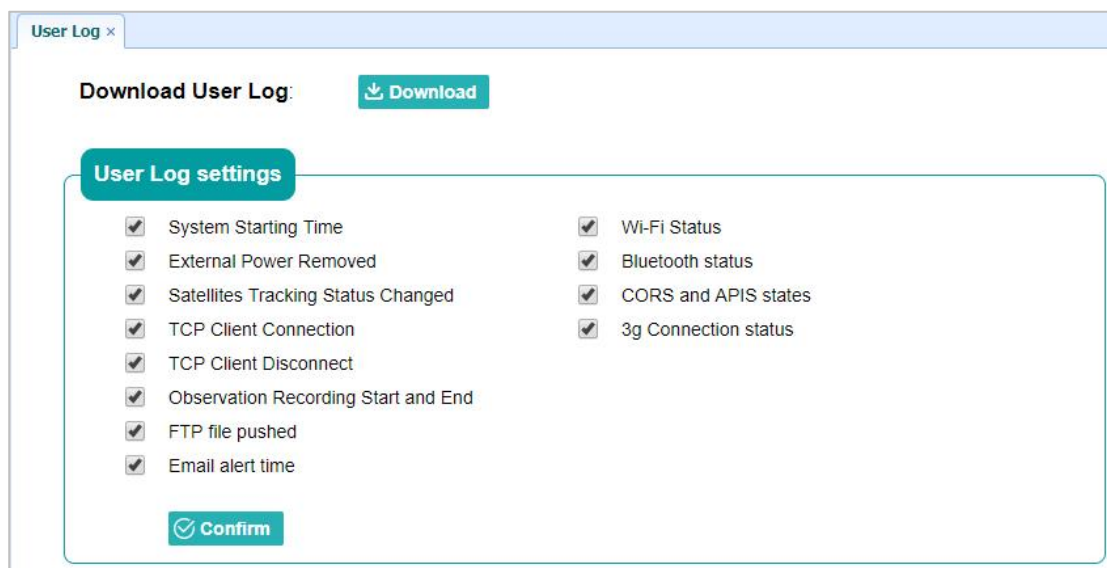
System Log ×

System Log Type: [Firmware Log](#)

[Download](#)

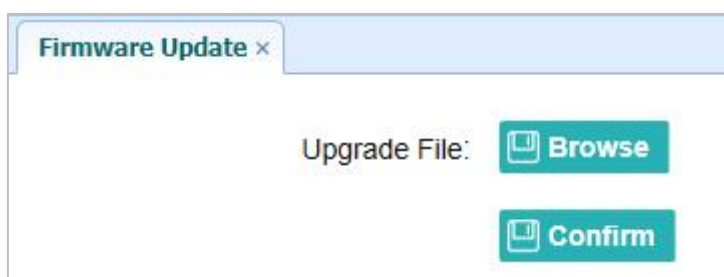
4.8.5 User Log Submenu

Use this submenu to download the user log. Tap Download to download current user log; Tick items that you want to see on the user log and tap confirm button to confirm selected user log.



4.8.6 Firmware Update Submenu

Use this submenu to load new firmware to the receiver across the network. Tap the **Browse** button to locate the upgrade file → tap **Confirm** button to confirm the selected upgrading file and start upgrading.

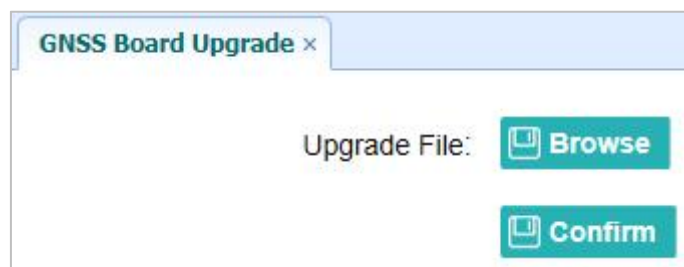


Notes

- It may take about 3 or 4 minutes to complete the firmware upgrading. Do not touch the power button or unplug the power until the upgrading process finishes, or damage will be caused to the receiver.
- The receiver will restart after the firmware upgrading is done, so users need to reconnect the receiver with your computer via Wi-Fi, and then log-in the receiver through a web browser to continue the configuration.

4.8.7 GNSS Board Upgrade Submenu

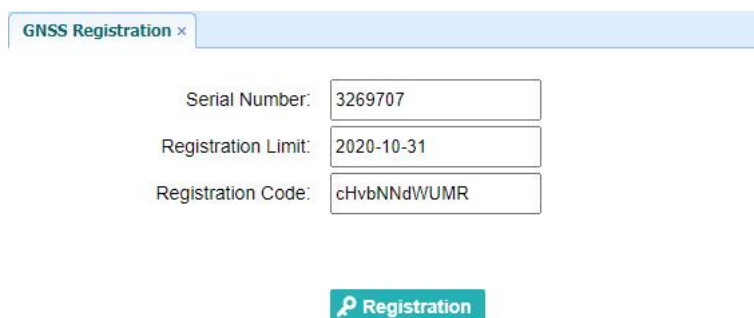
Use this submenu to upgrade GNSS Board. Use this submenu to load new board to the receiver across the network. Tap the **Browse** button to locate the upgrade file → tap **Confirm** button to confirm the selected upgrading file and start upgrading.



The screenshot shows a light blue header bar with the text "GNSS Board Upgrade ×". Below the header, the text "Upgrade File:" is followed by a teal button with a folder icon and the word "Browse". Below this, there is another teal button with a folder icon and the word "Confirm".

4.8.8 GNSS Registration Submenu

Use this submenu to register the receiver. Paste or enter the registration code to the *Registration Code* field → tap **Registration** button to complete the registration.



The screenshot shows a light blue header bar with the text "GNSS Registration ×". Below the header, there are three input fields with labels to their left: "Serial Number:" with the value "3269707", "Registration Limit:" with the value "2020-10-31", and "Registration Code:" with the value "cHvbNNdWUMR". Below these fields is a teal button with a key icon and the word "Registration".

FCC Warning**15.19 Labeling requirements.**

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

15.21 Information to user.

Any Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

15.105 Information to the user.

Note: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

FCC RF Radiation Exposure Statement:

1. This Transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.
2. This equipment complies with RF radiation exposure limits set forth for an uncontrolled environment.
3. This equipment should be installed and operated with minimum distance 20cm between the radiator and your body.

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